

MM-3M-ST, -F, -EX, -R/MM-4M-F

10 Position Encoder Resolution Data Sheet

Linear Motion: 10 mm HT Motor w/80 TPI Lead Screw

Gearhead Ratio	Max Travel Rate ²		Resolution ¹	
	Inch per second	mm per second	µinch per count	µm per count
16:1	0.260	6.60	19.5313	0.4960
64:1	0.064	1.65	4.8828	0.1240
256:1	0.016	0.41	1.2207	0.0310
1024:1	0.004	0.10	0.3052	0.0077

Rotary Motion: 10 mm HT Motor w/80:1 Worm Drive Ratio

Gearhead Ratio	Final Output	Max Travel Rate ²		Resolution ¹	
		degree per second	degree per count	degree per count	arc-second per count
16:1	1,280:1	93.74	0.00703125	25.3125	
64:1	5,120:1	23.44	0.00175781	6.3281	
256:1	20,480:1	5.86	0.00043945	1.5820	
1024:1	81,920:1	1.46	0.00010986	0.3955	

Note: For 16:1 gearhead there are 51,220 counts for 360° rotation.

Travel rate calculations:

Output Shaft RPM = RPM of motor/Gearhead Ratio
Distance per minute = Output shaft RPM x Lead (0.0125 in., 0.3175 mm)
Distance per second = Distance per minute/60
Distance in millimeter = inch/39.37 x 10⁻³
Distance in micrometer = inch/39.37 x 10⁻⁶

Encoder resolution calculations:

Encoder counts per shaft revolution = 40 encoder counts x Gearhead ratio
Minimum encoder count (inch) = Lead (0.0125 inch)/ Encoder counts per output shaft revolution
Minimum encoder count (millimeter) = Minimum encoder count (inch)/39.37 x 10⁻³
Minimum encoder count (micrometer) = Minimum encoder count (inch)/39.37 x 10⁻⁶

Conversion:

1 inch (in) = 25.4 mm
1 inch (in) = 25,400 µm
1 millimeter (mm) = 39.37 x 10⁻³ inch
1 micrometer (µm) = 39.37 x 10⁻⁶ inch
1 deg (deg) = 3,600 arc-second
1 arc-sec = 0.277 x 10⁻³ degree

Notes:

- 1) The lead values shown above in both travel rate and resolution calculations are for 80 (1/80) threads per Inch (TPI) leadscrews. For a 40 TPI leadscrew, substitute 0.025 inch lead.
- 2) Max travel rate calculated with motor armature running at a maximum speed of 20,000 RPM.
- 3) The 10 mm motors used with both the rotary and linear stages incorporate dual channel, 10 position, magnetic encoders. The resultant quadrature output is equal to 40 encoder counts per motor armature revolution.

The information contained in this data sheet is subject to change without notice. Critical dimensions or specifications should be verified with our technical support staff.

MTR-10-10E-HT MicroMini™ Motor

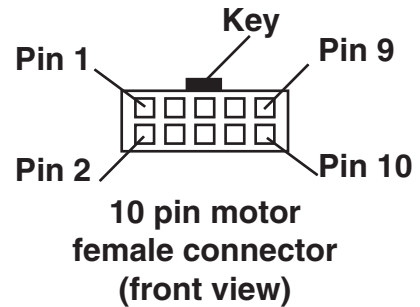
Linear 80 TPI/Rotary 80:1 Connection Specifications

Motor Type: MTR-10-10E-HT with planetary gearhead and magnetic encoder

Connector type: Dual row IDC

***Mate Part #(male pins):**

Pancon Part #057-010-115



Pin #	Name	Pin #	Name
1	Motor+	6	Motor -
2	Encoder+V	7	Limit ground
3	Encoder Ch A	8	No connection
4	Encoder Ch B	9	Reverse limit
5	Ground (case)	10	Forward limit

Electrical Specifications:

Supply Voltage Nom. (Volts)	6
Armature Resistance (Ohm) ±12%	10.8
Maximum power output (Watts) ⁽²⁾	0.81
Maximum Efficiency (%) ⁽²⁾	78
No Load Speed (RPM) ±12% ⁽²⁾	13,200
Friction Torque (at no-load speed)(mNm)	0.03
No Load Current (mA) ±50% ⁽³⁾	8
Stall Torque (mNm)	2.34
Velocity Constant (RPM/Volt)	2,231
Back EMF Constant (mV/RPM)	0.448
Torque Constant (mNm/A)	4.28
Armature Inductance (mH)	0.100
Speed/Torque gradient (RPM/mNm)	5,630
Maximum permissible speed (RPM)	12,000
Maximum continuous current (mA)	291
Maximum continuous torque (mNm)	1.21
Maximum power output at nominal voltage (mW)	810
Thermal time constant (s)	5/289

Encoder Specifications:

Supply Voltage	5 VDC Nominal
Max Voltage Supply	15 VDC
Operating Current	5mA Nominal @5 VDC
Signal Phase Shift	90°
Maximum Signal Frequency	7.2 KHz
Temperature Range	-40°C to +85° C
Output Signal Type	Square wave
Signal Rise Time	less than 5µs
Phase Relationship	Ch A leads CH B when motor rotation is clockwise as seen from shaft end.
Pulses per Revolution	10 (2 channels)
Quadrature	40 encoder counts
Output signal CMOS and TTL compatible	

Mechanical Specifications:

Mechanical Time Constant (ms) ⁽²⁾	7
Armature Inertia (g - cm ²)	0.12
Angular Acceleration (x10 ³ rad/sec ²) ⁽²⁾	195
Maximum rotor temperature	+85°C)
Axial Play	0.2mm
Shaft Play (measured at bearing)	
Radial	Less than 0.03mm
Axial	Less than 0.2mm
Thermal Resistance (C°/W)	
Rotor to Case	14
Case to Ambient	41
Maximum Shaft Load (N)	
Radial 1.5mm from flange	0.5 N
Axial @ standstill	20 N
Weight	8.8 g
Planetary Gearhead recommended	
max continuous input speed	5000 RPM

(1) Ratings are presented independent of each other

(2) Specified at nominal supply voltage

(3) Specified with shaft diameter = 0.8mm at no load

*Mating connectors available through National Aperture, Inc.

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